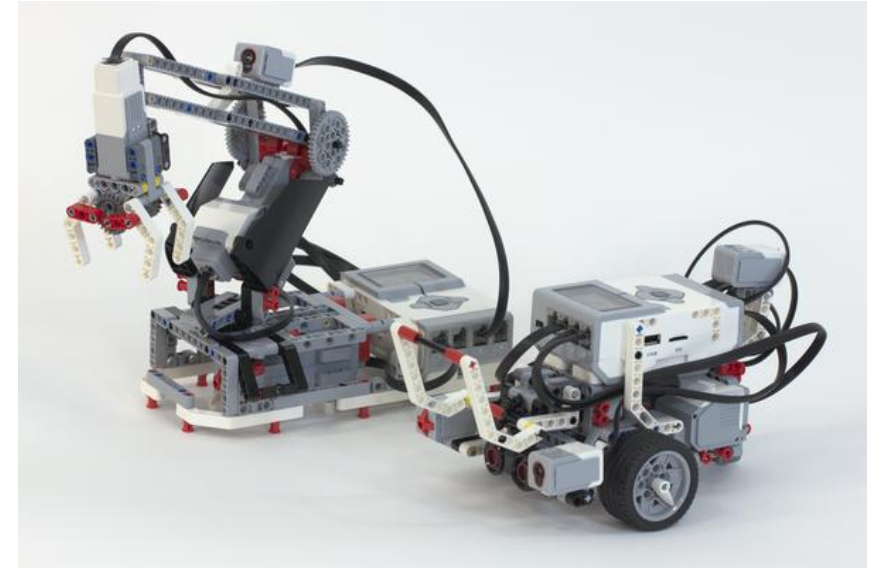


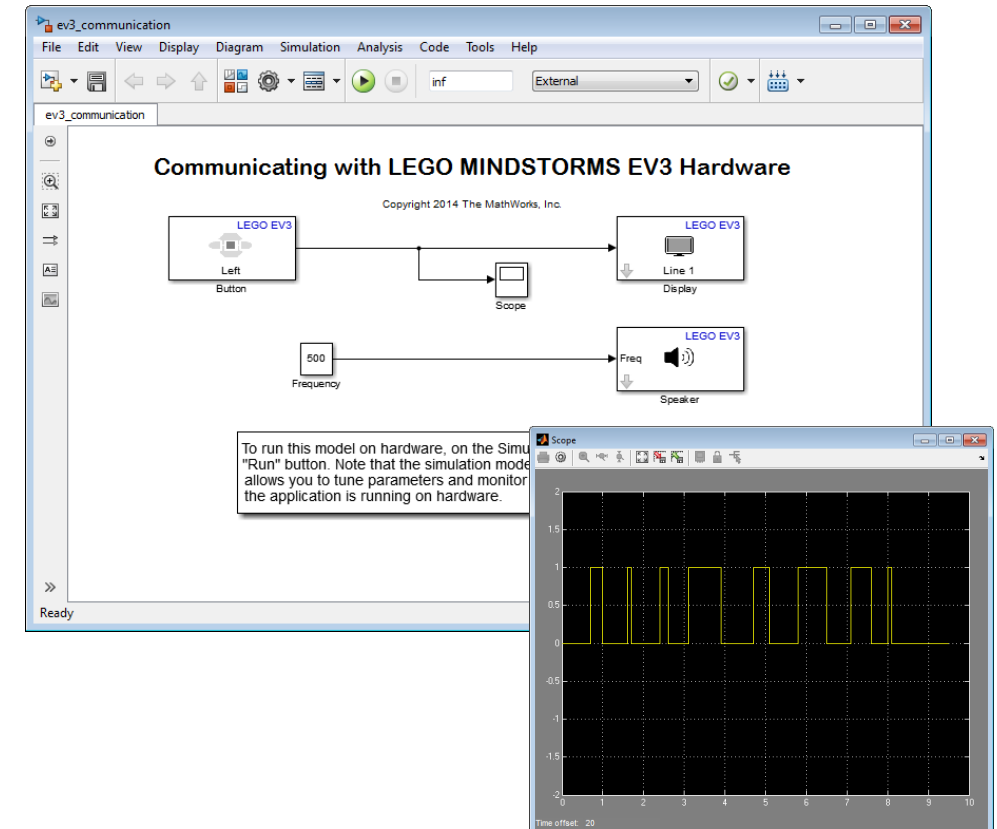
LEGO® MINDSTORMS® EV3 Programming using Simulink

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Agenda

- Introduction to LEGO MINDSTORMS EV3
- Software Setup
 - Installation of Simulink Support Package for LEGO MINDSTORMS EV3 Hardware
- Hardware Setup
 - Setup and connect EV3 to computer
 - Test with example: EV3 Communication
- Examples
 - Line Tracking Robot
 - Self Balancing Robot
- Wrap-up



Introduction to LEGO MINDSTORMS EV3

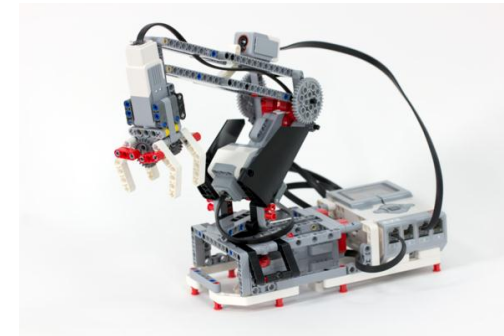
Introduction to LEGO MINDSTORMS EV3

- *What is it?*
 - LEGO MINDSTORMS is a programmable robotics construction set. EV3 is the third generation of the LEGO MINDSTORMS platform and the “EV” stands for evolution.
 - You can build a robot with provided instructions, or design and share your own creation
- *What is in a set?*
 - Intelligent EV3 Brick (ARM9-based microcontroller)
 - Sensors such as infrared, color, and touch
 - Actuators including three servo motors
 - Variety of LEGO structural and connection pieces
 - 2 sets available: Retail and Education



Introduction to LEGO MINDSTORMS EV3

- *What's the main difference between Retail and Education sets?*
 - [Retail set \(31313\)](#) has infrared sensor and beacon
 - [Education set \(45544\)](#) has rechargeable battery, gyro sensor and ultrasonic sensor
- *How much does it cost?*
 - Approximately \$350 US
- *OK, where do I get one?*
 - [LEGO Shop](#) (for Retail Set)
 - [LEGO Education](#) (for Education set)
 - Various online vendors ([Amazon](#) and others)



For more info: <http://www.lego.com/en-us/mindstorms/support/faq/>

Software Setup

Software Setup

- *What software do I need?*



- *MathWorks Software:*

- MATLAB and Simulink (also works with Student and Home versions) Release R2014a, or later
Note: LEGO EV3 support is available on 32-bit and 64-bit Microsoft Windows and 64-bit Linux.

- *Simulink Support Package for LEGO MINDSTORMS EV3 Hardware*

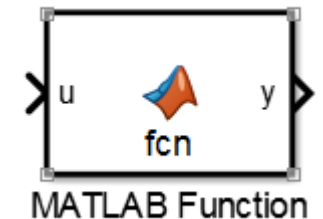
- *Optional: Compiler (for MathWorks software):*

You need a compiler if you want to use a [MATLAB Function Block](#) (MATLAB function which operates inside of Simulink and can be deployed to hardware)

- See **Supported and Compatible Compilers**

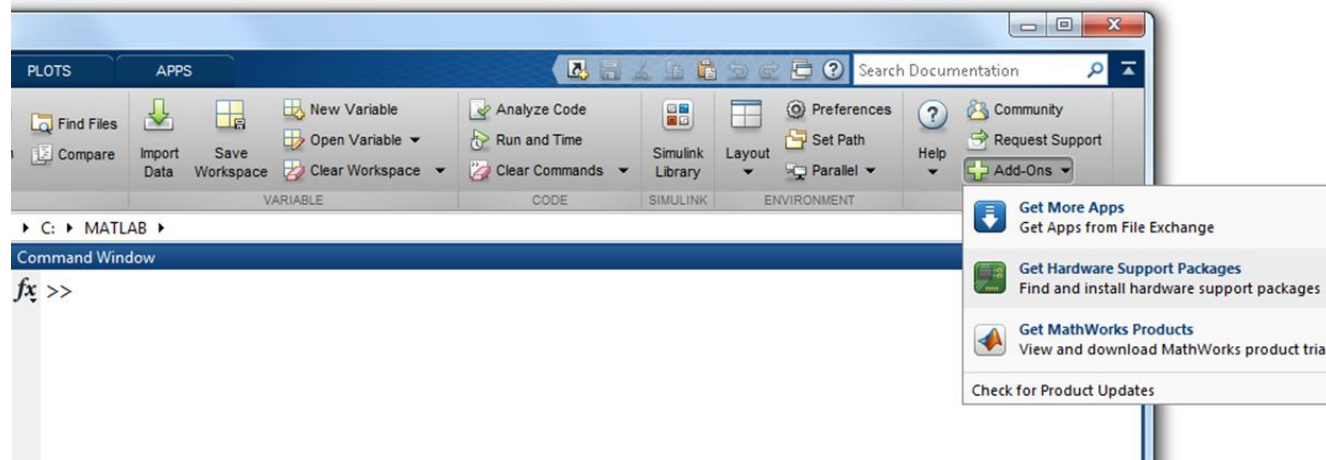
<http://www.mathworks.com/support/compilers/>

- For my 64-bit Windows 7 installation, I use [Microsoft Windows SDK 7.1](#) (available at no charge)



Simulink Support Package for LEGO MINDSTORMS EV3 Hardware

- *What is it?*
 - A set of Simulink blocks that allow you to generate programs that run on a LEGO MINDSTORMS EV3
 - It's downloadable and it's free!
- *Where do I get it?*
 - Get from the MATLAB Toolstrip: Add-Ons → Get Hardware Support Packages

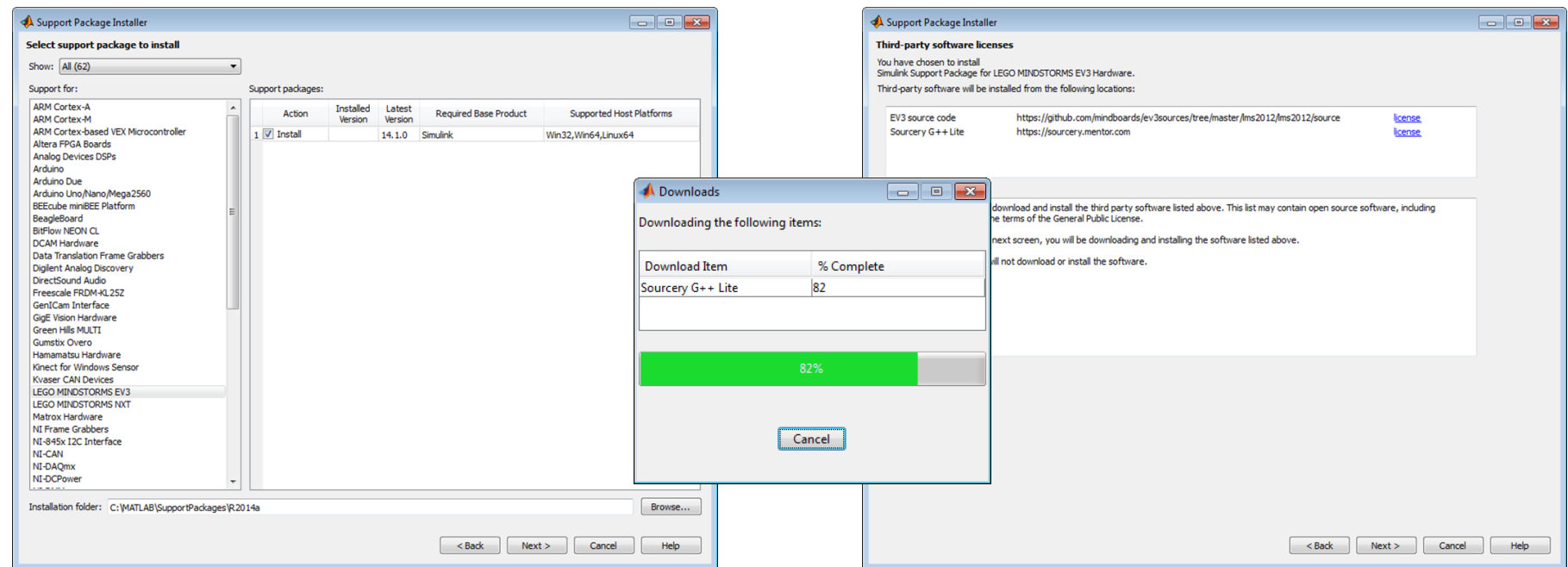


- Get from the MATLAB Command Line: `>> supportPackageInstaller`

Simulink Support Package for LEGO MINDSTORMS EV3 Hardware

- *Installation Process:*
 - The Support Package Installer will lead you through the installation process and install all the software you need to run on a LEGO MINDSTORMS EV3 from Simulink

Let's go get it!



Summary: Simulink Support Package for LEGO MINDSTORMS EV3 Hardware

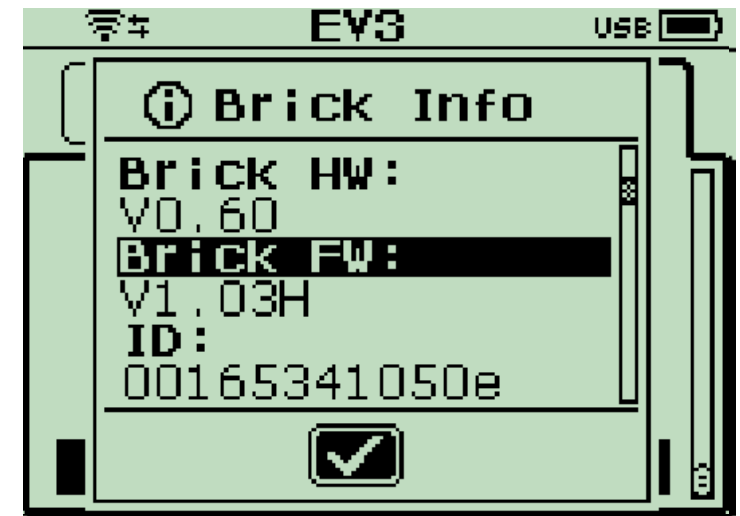
- Support Package Installer installs all the software elements you need to connect to and run on a LEGO MINDSTORMS EV3

EV3 source code
Sourcery G++ Lite

<https://github.com/mindboards/ev3sources/tree/master/lms2012/lms2012/source>
<https://sourcery.mentor.com>

[license](#)
[license](#)

- Requires MathWorks Account Login
 - (but don't worry if you don't have one, you can create one when you get to the screen)
- Verify LEGO EV3 Firmware Version
 - In the EV3 Brick Interface, go to the settings and select **Brick Info**.
 - Check that **Brick FW** is V1.03E or later.
 - If the firmware is earlier than V1.03E, use the *LEGO® EV3 Software* to update the firmware.



Hardware Setup

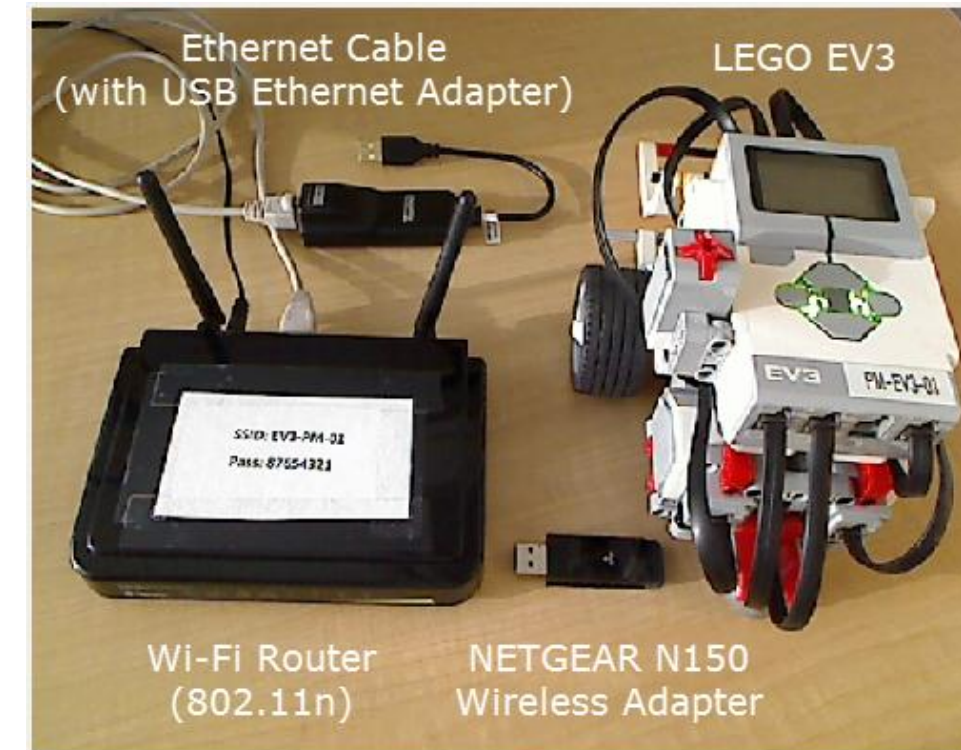
Hardware Setup

- *What hardware do I need?*
 - LEGO MINDSTORMS EV3 kit
 - [LEGO MINDSTORMS EV3](#) retail set (31313)
 - [LEGO MINDSTORMS EV3 Education Core set](#) (45544)
 - Wi-Fi Router (802.11n)
 - NETGEAR N150 Wireless Adapter (WNA1100)
 - Recommended by LEGO
 - Connectivity from host computer to Wi-Fi router
 - Can directly connect via Wi-Fi adapter in host computer
 - Or can connect via Ethernet cable from host computer
 - Optional but useful:
 - EV3 Rechargeable DC battery (45501) + DC Charger (8887)



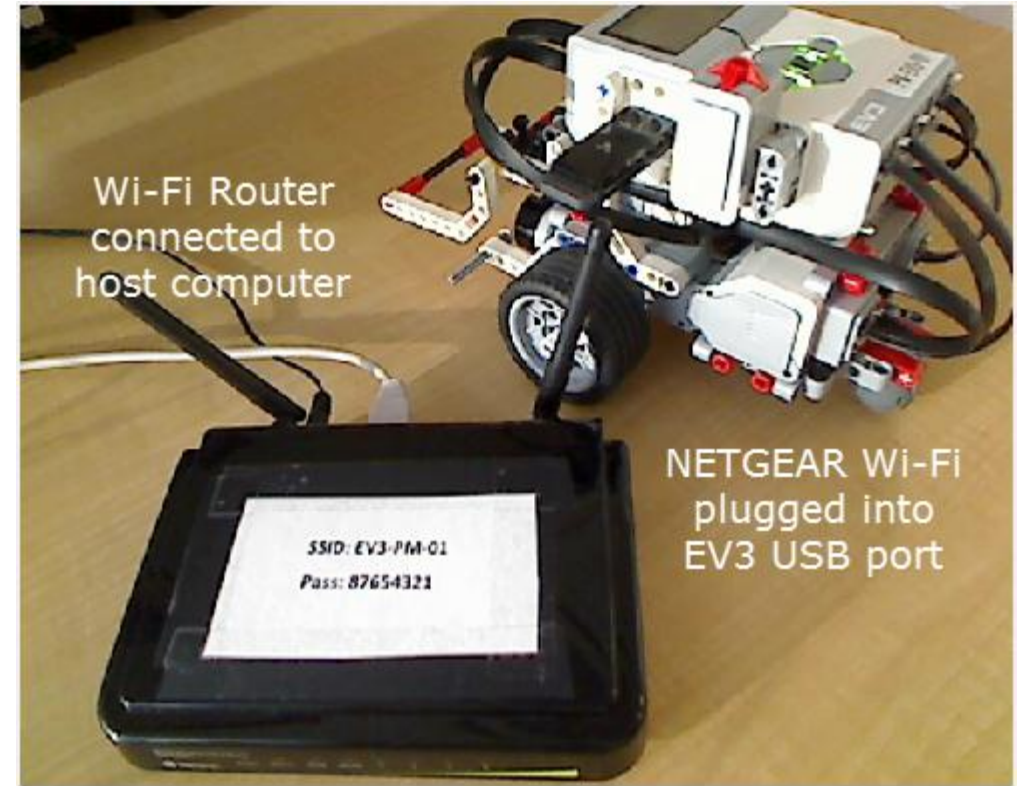
Robot Educator

- Build directions in Education Core Set and [online](#)



Hardware Setup

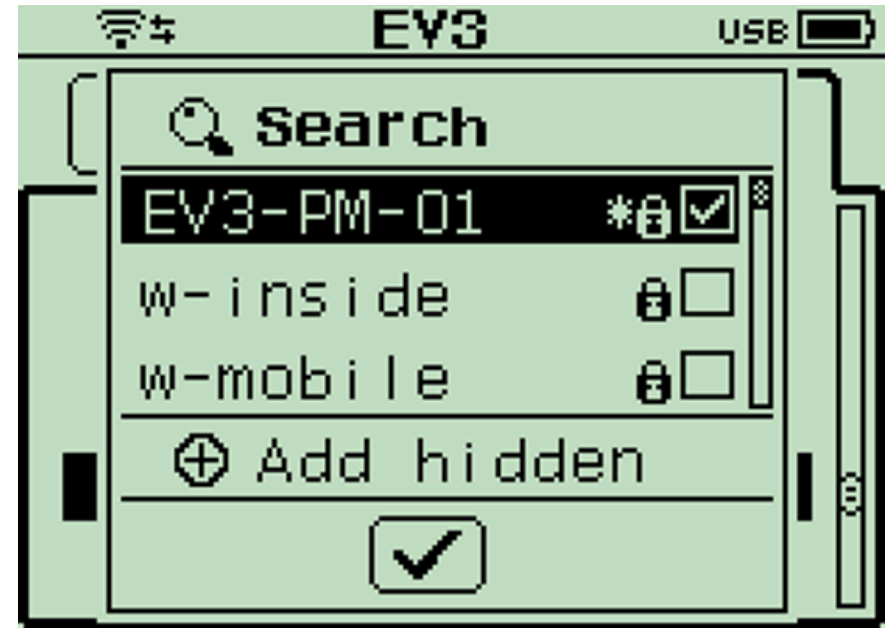
- *Connect up the hardware*
 - Power on Wi-Fi Router
 - Wi-Fi Router Configuration:
 - DHCP (dynamic host configuration protocol)
 - Encryption = None or WPA2
 - Connect Wi-Fi router to host computer
 - Use Wi-Fi adapter or Ethernet cable to port 1
 - Plug Wi-Fi dongle into EV3
 - Power on EV3 by pressing and holding center button
 - Wait for LEGO EV3 to boot up



Hardware Setup

- *Connect EV3 to Wi-Fi Router*

- In the EV3 Brick Interface, go to settings and select `WiFi`
- Select `WiFi` and turn it on (look for checkmark in the box and WiFi icon on top left)
- Select `Connections`
- Select your Wi-Fi Router SSID and select `Connect`
- Select your Encryption
 - EV3 only works with Encryption settings of None or WPA2, so make sure your Wi-Fi router is configured correctly
- Type in your Wi-Fi Router password using the EV3 buttons and select enter
- Look for check mark next to your Wi-Fi Router SSID



Hardware Setup

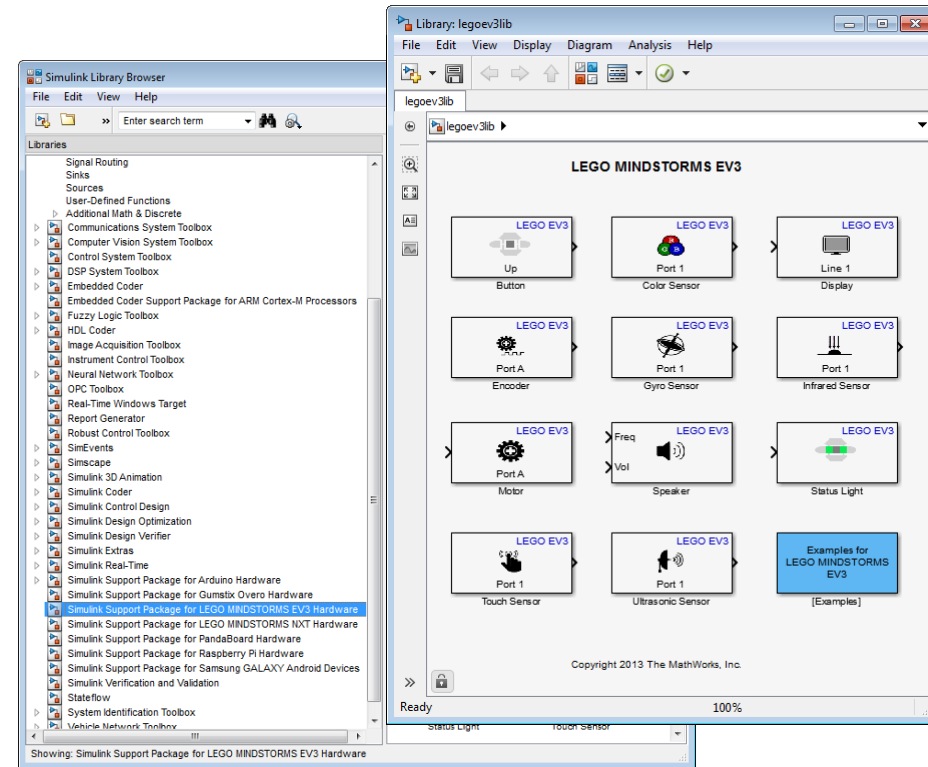
- *Get EV3 IP Address*
 - In the EV3 Brick Interface, go to the settings and select `WiFi`
 - Click center button with WiFi Router selected
 - Note down the IP Address of your brick
 - IP Address is in a range determined by your Wi-Fi Router configuration
 - IP Address is dynamically allocated – it may change next time you power on your EV3 brick!



Let's go test it!

Summary: Simulink + LEGO EV3 Testing

- Check for Support Package Installation
 - Simulink Support Package for LEGO MINDSTORMS EV3 Hardware should be in your Simulink Library
 - Can also type at MATLAB Command line:
`legoev3lib`
- Test your connection (computer to LEGO EV3)
 - Type at the MATLAB command line:
`!ping ip.add.re.ss`
 - OR type at the MATLAB command line:
`legoev3('ip.add.re.ss')`



```
>> !ping 192.168.10.102

Pinging 192.168.10.102 with 32 bytes of data:
Reply from 192.168.10.102: bytes=32 time=5ms TTL=64
Reply from 192.168.10.102: bytes=32 time=3ms TTL=64
Reply from 192.168.10.102: bytes=32 time=3ms TTL=64
Reply from 192.168.10.102: bytes=32 time=3ms TTL=64

Ping statistics for 192.168.10.102:
    Packets: Sent = 4, Received = 4, Lost = 0 (0% loss)
    Approximate round trip times in milli-seconds:
        Minimum = 3ms, Maximum = 5ms, Average = 3ms
fx >>
```

```
>> legoev3('192.168.10.102')

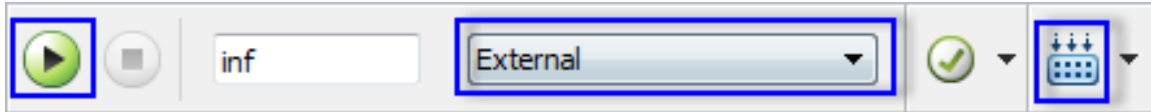
ans =

legoev3 with properties:

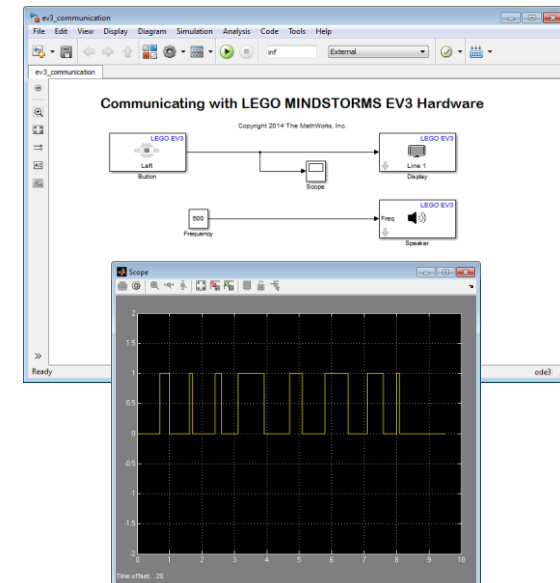
    ipAddress: '192.168.10.102'
fx >>
```

Summary: Simulink + LEGO EV3 Testing (con't)

- Open LEGO EV3 Communication model: `ev3_communication`
- Click Tools -> Run on Target Hardware -> Options
 - Check to make sure Target hardware = LEGO MINDSTORMS EV3.
 - Also check / update the IP Address.

- Click Run button 
 - We used the “External” simulation mode.
 - External mode allows you to tune parameters and monitor signals in the model while the application is running on hardware
 - You can use “Deploy to Hardware” button if you want to run on the hardware with no interaction from the host

- The model is now running on the LEGO EV3 robot



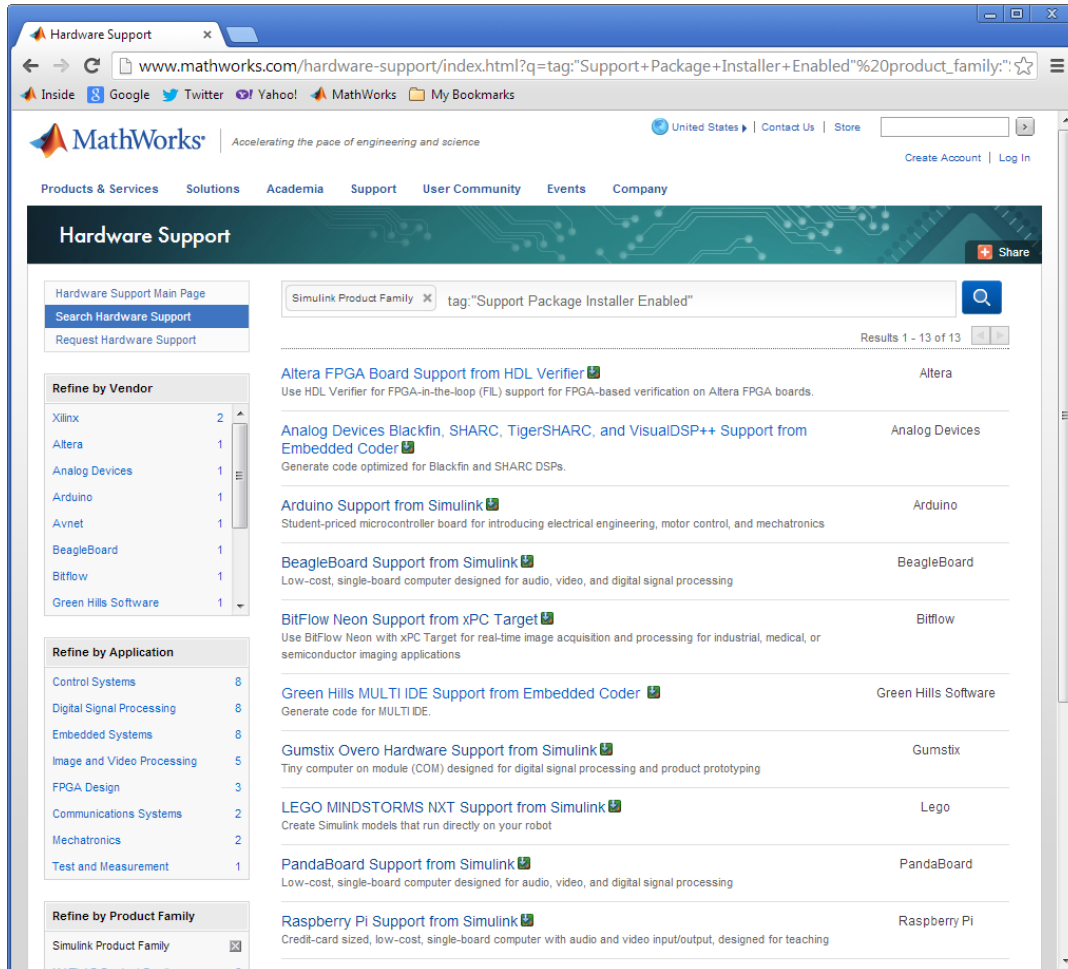
Examples

-
- The screenshot displays the MATLAB/Simulink interface. The main window shows a Simulink model titled "ev3_linetracking". The model is a line tracking control system. It includes blocks for "ReferenceVelocity" (Desired States), "StatesError" (Forward), "Velocity Control", "LeftMotorT" (Left Motor Encoder), "RightMotorT" (Right Motor Encoder), "LightSensor" (State Estimation), "Light Sensor/Monitor", "RightMotor", "LeftMotor", "Motors", "White Value" (750), "Black Value" (500), "White" (Desired Light), "Black" (Desired Light), "LightError" (Turning), and "Line Tracking Control". The model is connected to a video feed window titled "Video Preview - Logitech Webcam Pro 9000", which shows a small robot on a black line track.

-
- The screenshot displays the MATLAB/Simulink interface. The main workspace shows a Simulink model titled 'EV3_HW_Balance_Move'. The model is composed of two primary subsystems: the 'Controller Subsystem' and the 'Self Balancing Robot Hardware Subsystem'. The 'Controller Subsystem' contains 'Sensors' and 'PWM' blocks. The 'Self Balancing Robot Hardware Subsystem' contains 'Actuators' and 'Raw Sensors' blocks. A signal line connects the 'PWM' block to the 'Actuators' block. A video preview window in the bottom right corner shows a real-time feed of the LEGO EV3 robot on a white surface with a black wavy line. The status bar at the bottom indicates 'Ready' and '192%' zoom.

Wrap-Up

Simulink Hardware Support



<http://www.mathworks.com/hardware-support/home.html>



Arduino



Lego EV3 & NXT



Raspberry Pi



BeagleBoard



PandaBoard



Samsung GALAXY

Selected Simulink Supported Hardware:

- LEGO® MINDSTORMS® EV3 and NXT (\$350)
- Arduino® Uno, Due, Mega 2560 and more: (\$30-\$70)
 - Also support for Ethernet and WiFi Shields
- Raspberry Pi Model B and B+ (\$40)
- BeagleBoard-xM (\$150) and PandaBoard (\$180)
- Samsung GALAXY Android Devices (\$50-\$500)

Available in Student and Home Versions!

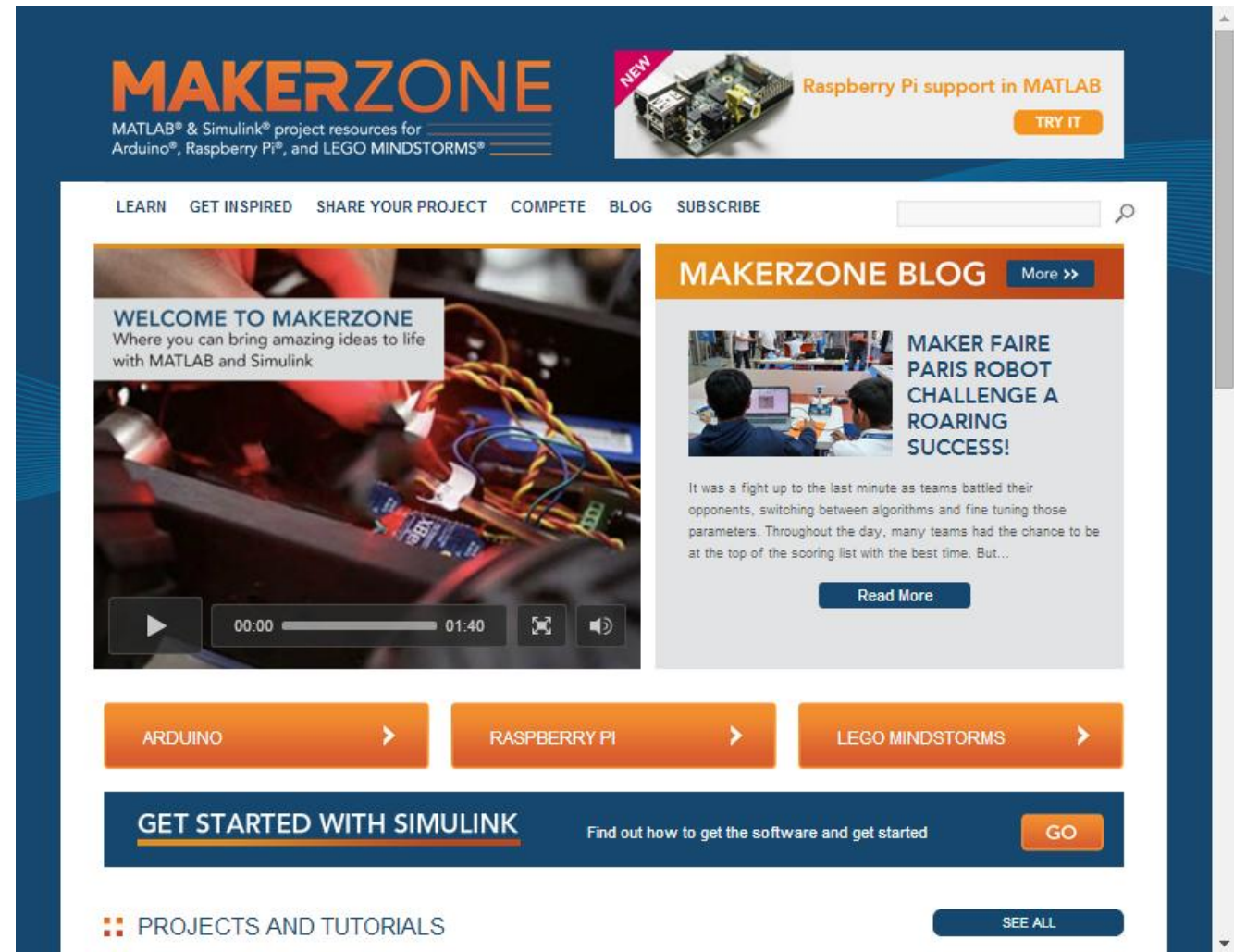
Additional Resources

makerzone.mathworks.com

www.mathworks.com/academia

www.mathworks.com/student_version

www.mathworks.com/matlab-home



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